



Hypersonic Vehicle (HSV) Modeling

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HSV Concentration

MACCS Kickoff Meeting

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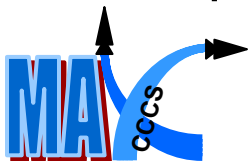
Team

- U of M Faculty: Carlos Cesnik (PI), Jim Driscoll
- Current students: Nathan Falkiewicz, Torstens Skujins, Nathan Scholten, Sean Torrez, plus Post-doctoral fellow (TBD)
- AFRL collaborators: Mike Bolender, David Doman, Mike Oppenheimer



Overview

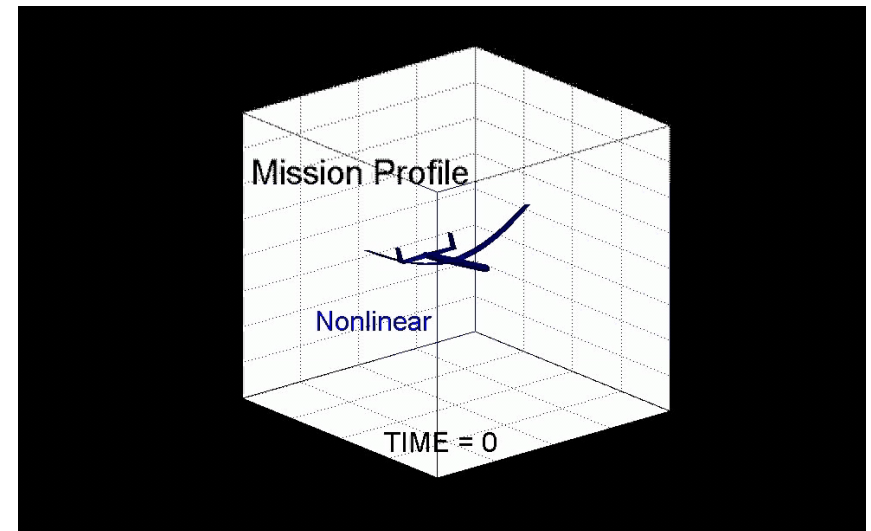
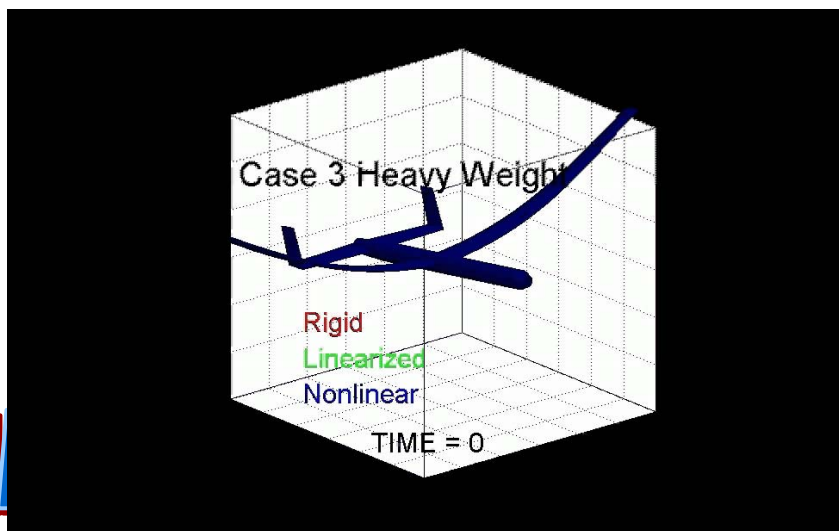
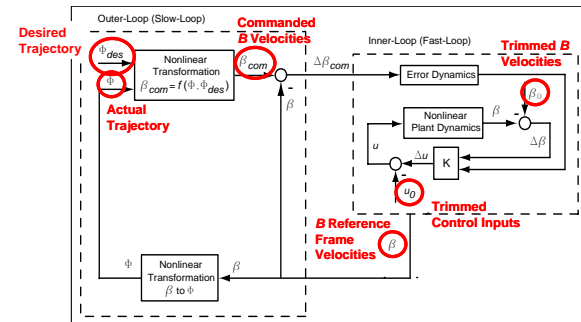
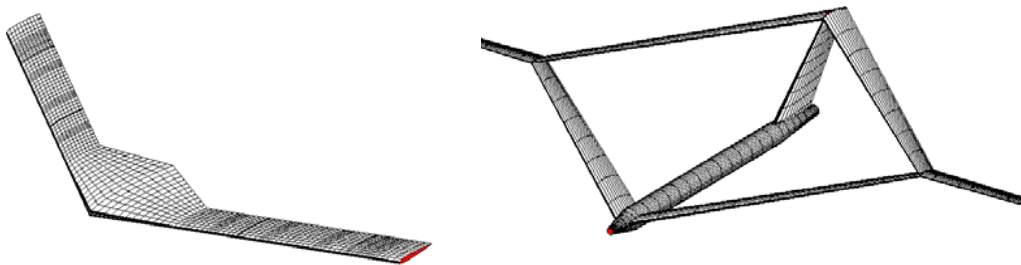
- Challenge: strong interactions among aerodynamics, elastic airframe and control effector deformations, heat transfer, and propulsion system (itself tightly integrated into the lifting body)
- Focus in two main areas:
 - development and validation of simple (low-order) control models that can characterize the main aerothermoservoelastic effects coupled with propulsion in a 6 DOF flight dynamics simulation of HSV; and
 - determination on how to appropriately modify vehicle configuration to improve its dynamic controllability without compromising vehicle performance.
- All done in close collaboration with AFRL/VACA researchers who will provide primarily the control design and modeling expertise as part of the Collaborative Center.



Sample Relevant Work at UM

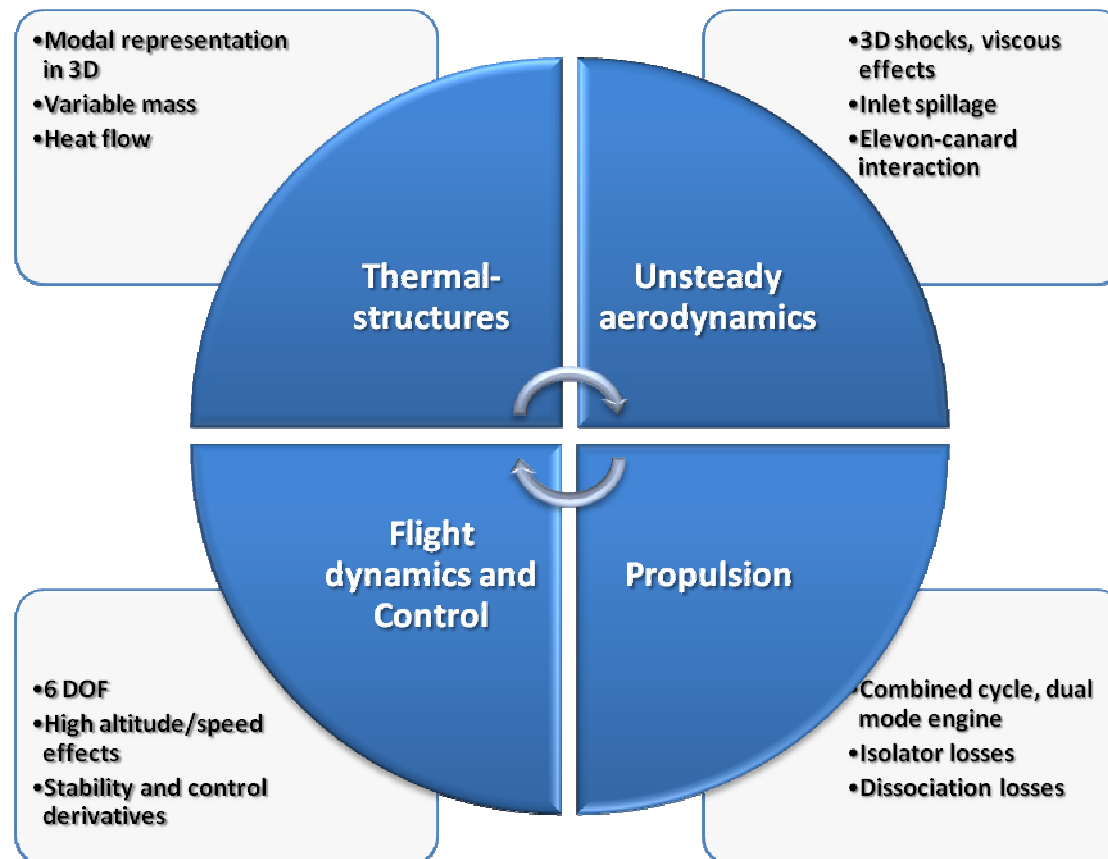
Very Flexible HALE Aircraft (Sensorcraft-class)

- **Aeroservoelastic formulations at different complexity levels**
 - Target preliminary vehicle and control design and more detailed analysis
 - Able to simulate 6-DOF with fully flexible vehicle
- **Numerically investigate aeroelastic response under nonlinear effects**
- **Model different vehicle configurations**



Disciplinary Components of HSV

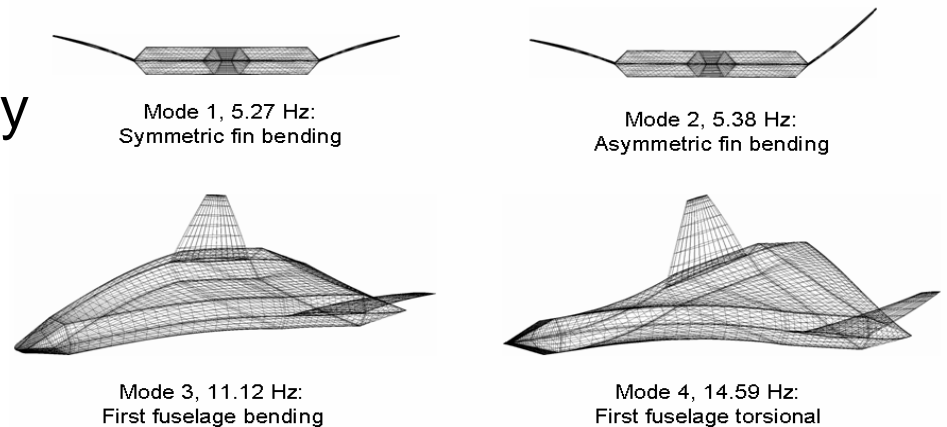
- Four main component areas to be address in the study



Thermo-structural Dynamics Modeling

- Structures defined by flexibility and inertia effects

- different options to characterize deformations



McNamara and Friedmann, 2006

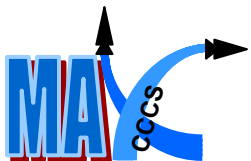
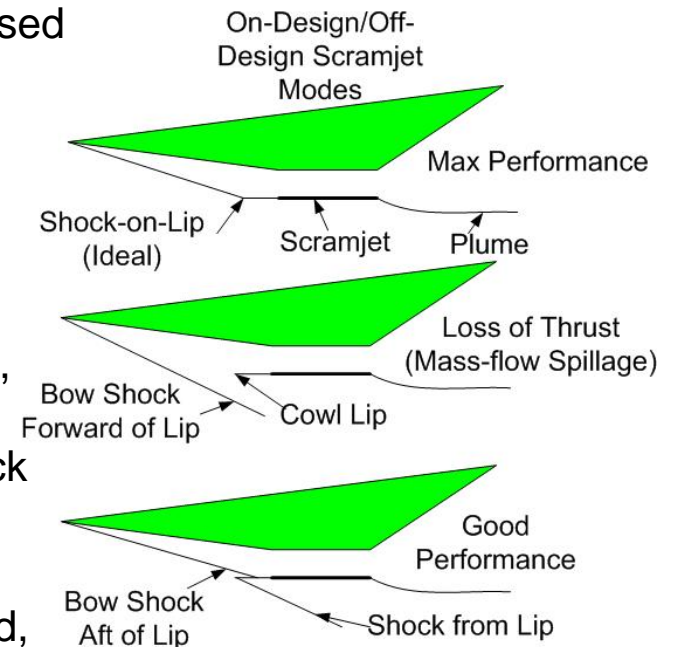
- Heat issues:

- thermo effects on the elastic characteristics of the vehicle
 - Dependent on the structural layout and material stacking sequence
→ need detailed model of the structure to assess impact on vehicle response
- temperature gradients in the structure will impact
 - the reference vibration modes and static deflections of the control surfaces and possibly of the entire vehicle (mainly due to thermal stresses and material property degradation with temperature)
 - fuel temperature in the tanks (which can define optimum flight trajectories).



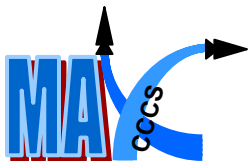
Unsteady Aerodynamics Modeling

- Complex environment of unsteady, viscous, non-equilibrium, reacting flow
- Current models limited to longitudinal dynamics
 - Stead state shock/expansion geometry determined based on the Oblique Shock Theory
 - Superimposed unsteady aero effects based on piston theory
- Several issues—AFRL has identified needed improvements in the following areas:
 - unsteady pressure over the entire wetted surface area, including lateral aerodynamics,
 - spillage effects caused by the location of the bow shock with respect to the inlet during vehicle bending,
 - coupling of the aerodynamics and the heat transfer,
 - control surface aerodynamics, including elevon, canard, and elevon-canard interactions,
 - viscous effects.



Propulsion Model

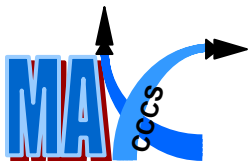
- Combined cycle engine as an integral part of the vehicle structure
- Model must contain (AFRL):
 - engine forces & moments related to bow shock/engine spillage, pressures on aft underbody
 - forces depend on fuel/air ratio, diffuser area ratio, cowl leading edge
- We will work with AFRL to improve modeling of:
 - inlet/isolator shock losses,
 - scramjet dissociation / frozen flow losses
 - real gas effects, finite-rate chemistry
 - how pressure varies with distance inside engine
 - thermal choking limitations to fuel-air ratio
 - RBCC (or TBCC) cycle analysis, ram-scram transition
 - boundary layer effects (effective duct shape change)



Driscoll will discuss more about it next

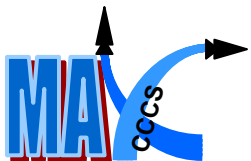
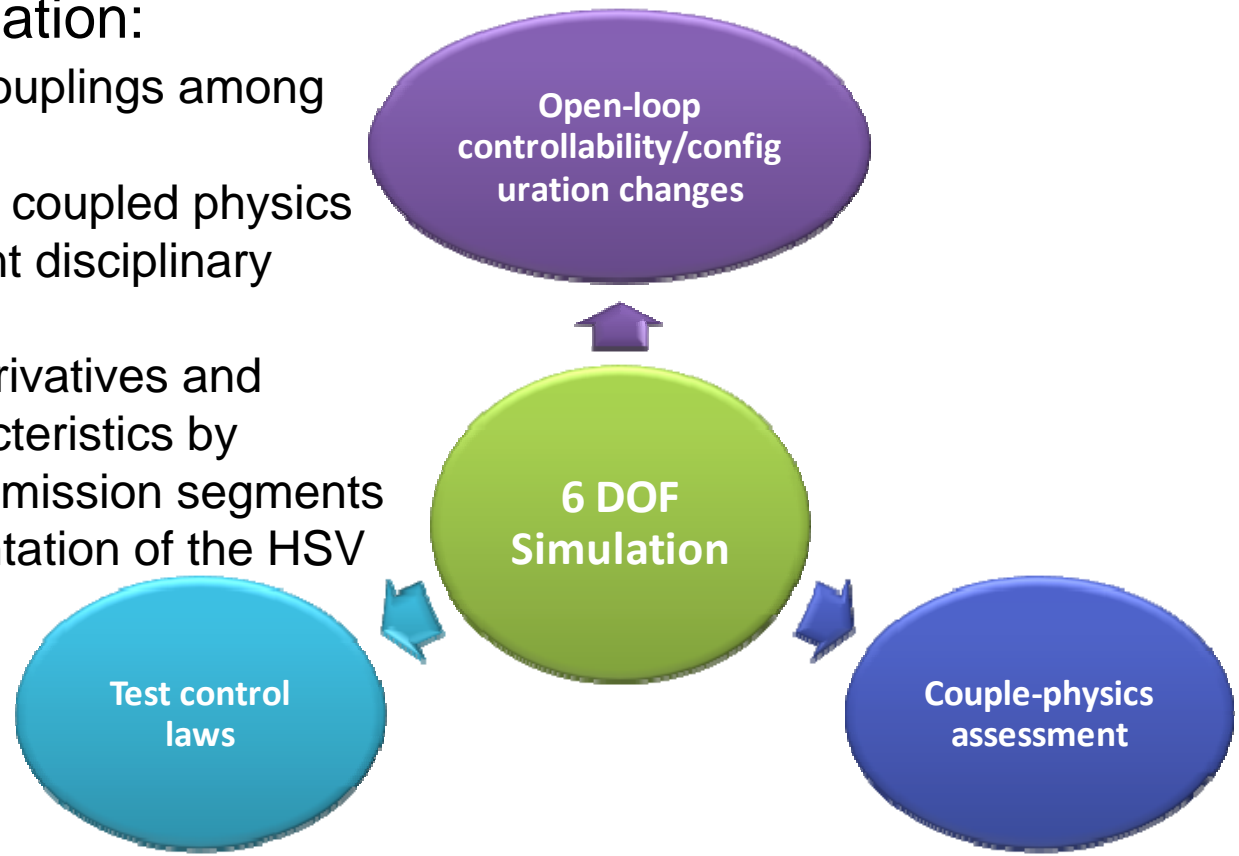
Flight Dynamics Model

- Free flight simulation of the flexible HSV is the ultimate goal
 - Lateral dynamics will bring new modes that may couple with the longitudinal ones (short-period mode; phugoid-like mode, although independent of speed; and a height mode, typically not seen in conventional subsonic vehicles)
- Development of the nonlinear rigid 6 DOF model based on AFRL's current planar (2D) formulation
- Solution of combined flight dynamics/aerothermoelasticity problem
 - numerical stability for long term simulations
 - integration of the disciplines and models



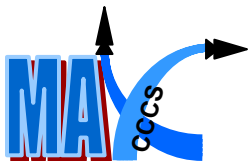
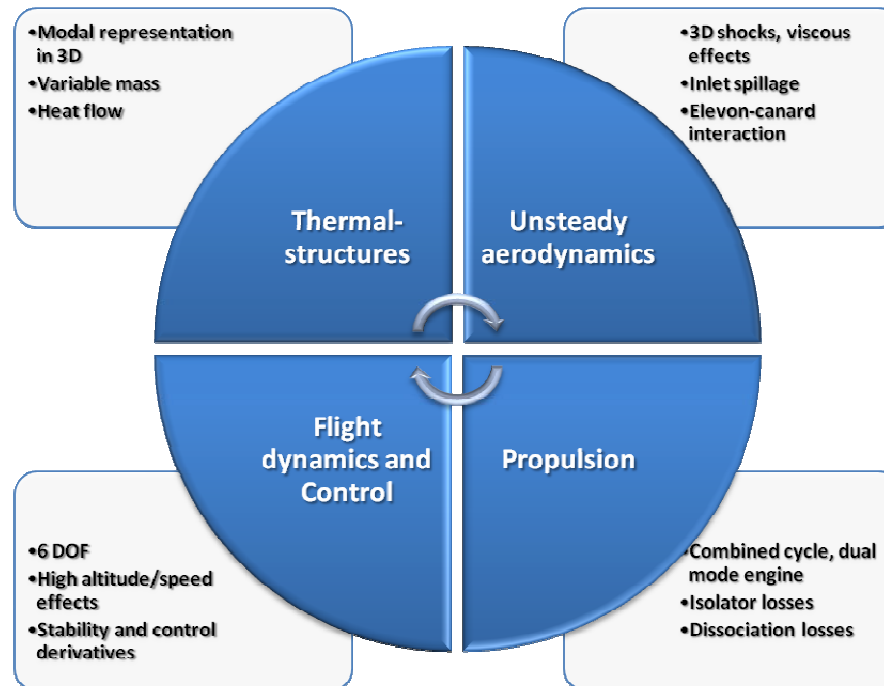
Vehicle Configuration and Sensitivities for Dynamic Controllability

- Issue: *How to appropriately modify the vehicle's configuration to improve its dynamic controllability without compromising its performance?*
- Create 6 DOF Simulation:
 - Simulate open-loop couplings among different disciplines
 - Quantify the effects of coupled physics coming from the different disciplinary areas
 - Determine stability derivatives and overall root locus characteristics by linearization at different mission segments
 - Serve as the representation of the HSV for testing control laws



Overview of Modeling Approach

- Two main thrusts for HSV modeling:
 - (Low-order) *control models*
 - (High-fidelity) *reference models*along with a *control evaluation model*.



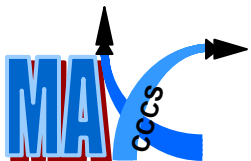
(Low-order) Control Models

- Guiding principle: *represent the important physics that will drive the controllability of the HSV with the lowest number of states possible* (suitable for control studies)
- Approach: create *representative* low-order models for the thermo-structural dynamics, unsteady aerodynamics, engine dynamics, flight dynamics, and all their couplings from combination of:
 - (Direct) fundamental models
 - Reduced-Order Models (ROM) from high-fidelity modelsand then assess the validity of the models

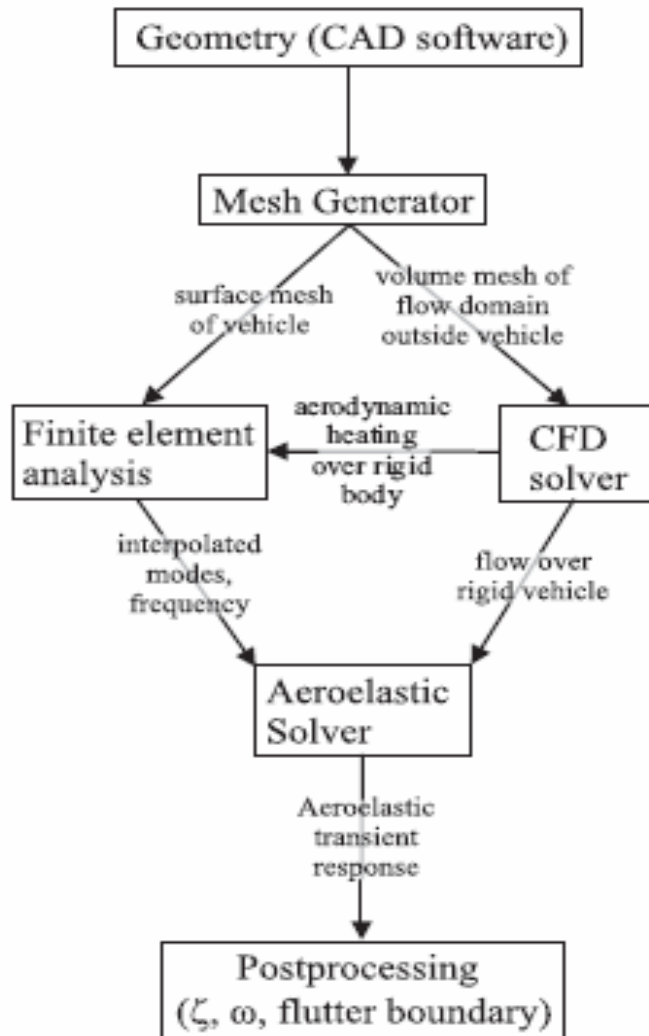


(High-fidelity) Reference Models

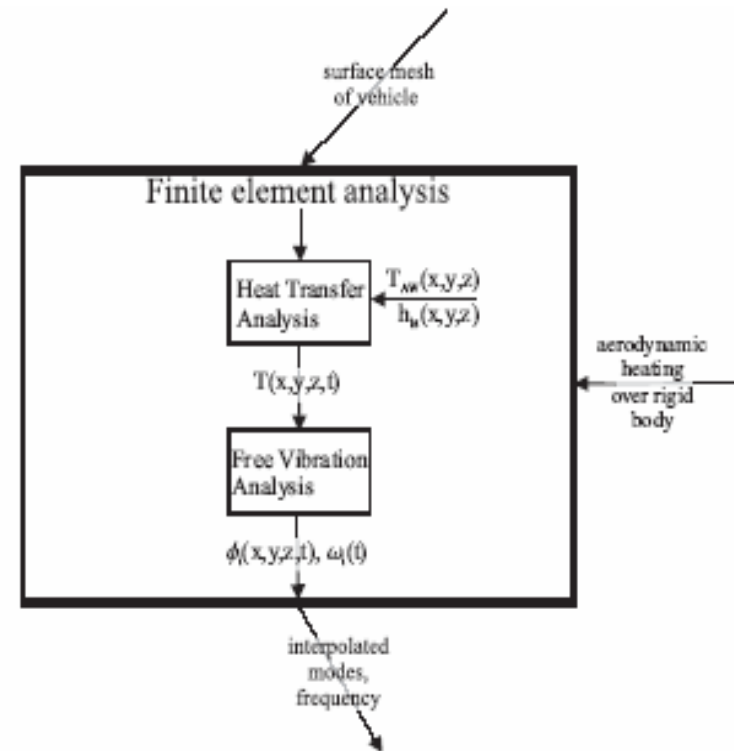
- High-fidelity computational models will be used to:
 - create the “truth” model for accuracy assessment of the control models
 - serve the basis for creating ROMs directly from its results
- Approach: codes (and models when available) will be used for this study and no code development effort is expected
 - MSC.Nastran for thermo-structural dynamics
 - FUN3D for unsteady aerodynamics
 - VULCAN for engine dynamics



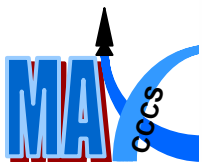
Example: High-fidelity Aerothermoelastic Model



(a) Aerothermoelastic Solution Procedure.



(b) Finite Element Analysis.



Example: ROM based on Volterra Series

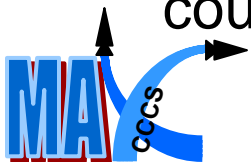
- Impulse response method for (linear or nonlinear) time-invariant systems
- Successfully applied as Aerodynamic Impulse Response method for different flight regimes and different codes, including CFL3D (Silva, 1997, 2007; Guendal and Cesnik, 2001)
- Core of the process is based on discrete system identification

$$y(i) = h_0 + \sum_{k=0}^N h_1(k)u(i-k) + \sum_{k_1=0}^N \sum_{k_2=0}^N h_2(k_1, k_2)u(i-k_1)u(i-k_2)$$

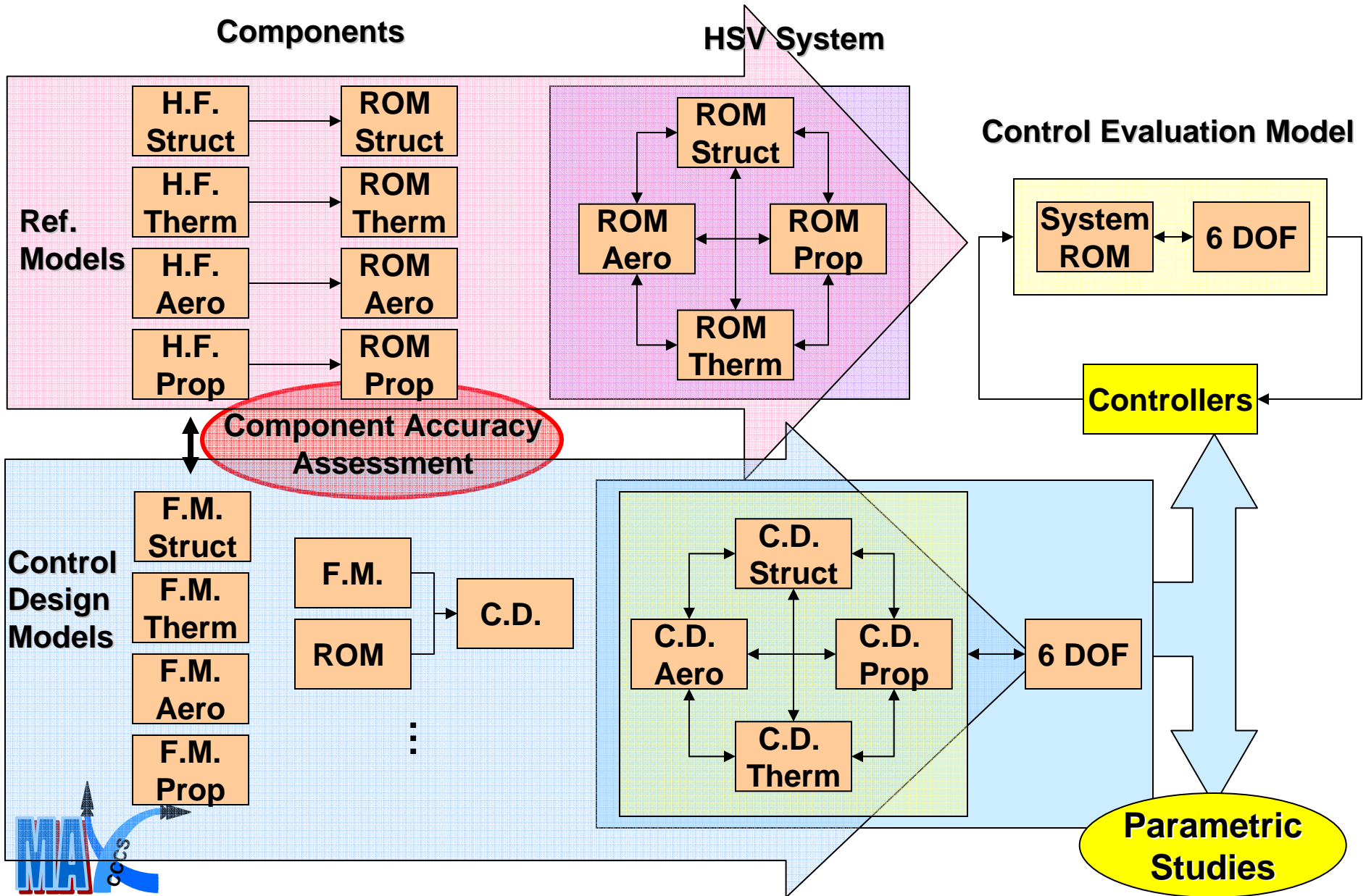
Diagram illustrating the Volterra series equation with annotations:

- response**: points to $y(i)$
- excitation**: points to $u(i-k)$
- ID'ed Kernels**: points to $h_1(k)$ and $h_2(k_1, k_2)$

- Applicability to the other disciplines and to the combined coupled problem will be investigated



Proposed Modeling Approach



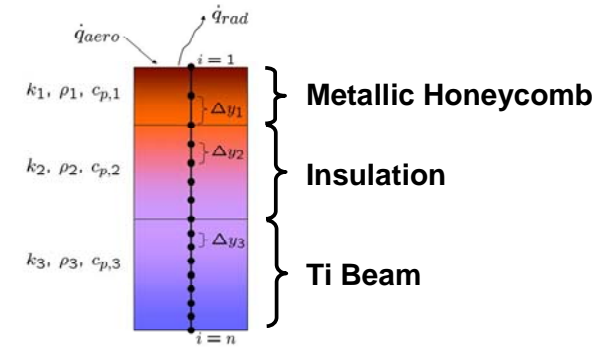
Schedule

	Year 1	Year 2	Year 3	Year 4
Fundamental Models				
Unsteady aerodynamics				
add real gas properties, boundary layer to 2D model	█			
extend AFRL model to lateral aerodynamics		█		
add real gas properties, boundary layer to 3D model			█	
Thermo-structures				
1D heat flow and connection to planar beams	█			
consider dynamics of more complex beams		█		
spatial variation of thermal properties			█	
Propulsion				
add 2D engine efficiency factors for shock	█			
add 3D engine efficiency factors for shock		█		
losses, dissociation, thermal choking			█	
Component Accuracy Assessment				█
Reference Models				
Baseline 3D vehicle	█			
Unsteady aerodynamics FUN3D		█		
Thermo-structures: NASTRAN			█	
Propulsion: VULCAN	█			
Component ROMs		█		
System ROM			█	
Control Evaluation Model			█	
Control Design Models				
Selection from F.M. and ROM models			█	
System C.D.				█
Integration of System C.D. and 6 DOF			█	
Flight Dynamics (and Control)				
Enhanced 2D FD + aerothermoelastic + propulsion	█			
New 6DOF + aerothermoelastic + propulsion		█		
Sensitivity Studies on Configuration				
Component		█		
System			█	
Annual Meetings	x	x	x	x



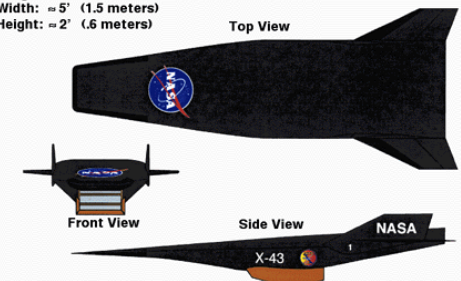
First Year Activities

- Fundamental model development
 - extend AFRL's piston theory-based aero model to include B.L.'s displacement thickness effects
 - model elevator-canard interaction (started over the summer, Skujins and Oppenheimer)
 - model 1D thermo-structural response to extract parameter corrections for HSV structure
 - add realistic efficiency factors to propulsion model
- Reference models
 - setup codes and input files for reference case
 - define fundamental information flow between components and define key I/O for ROM generation
 - create baseline structural layout for 1D thermo analysis
 - run 2-D propulsion model to identify critical issues
- Select baseline vehicle
 - stretched X-43A (to 100-ft length) with NASP-based interior structural layout (info needs to be accessible)



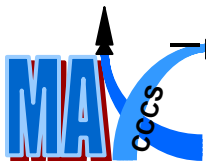
X-43A Vehicle

Length: ~ 12' (3.7 meters)
Width: ~ 5' (1.5 meters)
Height: ~ 2' (.6 meters)



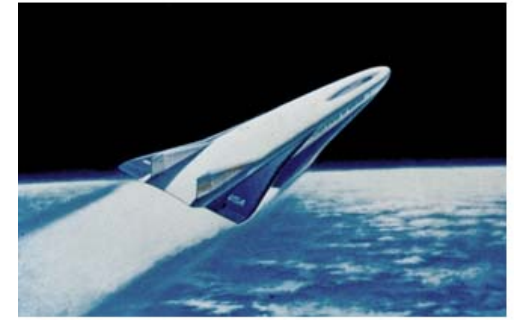
Initial Task Assignments

- Graduate students:
 - Torstens Skujins (MS/PhD): unsteady aerodynamics modeling (canard-elevon interaction, steady CFD coupled with piston theory, boundary layer effects) and flight dynamics
 - Nate Falkiewicz (MS/PhD): thermo-structural modeling (1D heat flow through the thickness and its connection with structural dynamics model parameters, FEM modeling of representative structure)
 - Nate Scholten (MS): High-fidelity aerodynamics and propulsion modeling
 - Sean Torrez (MS/PhD): propulsion modeling (1D efficiency factor corrections, engine cycle code reference modeling)
 - TBD: Aerothermoelastic ROM generation and system integration for controls applications
- Post-doctoral fellow (TBD):
 - Baseline 3D vehicle definition
 - H.F. code and input setup





Concluding Remarks



- Highly coupled multidisciplinary problem modeling effort for control design and simulation
- Several specific challenges lay ahead—group is highly motivated and bring disciplinary expertise and prior experience in similar issues
- Good start with student summer activity (Torstens Skujins) at AFRL—more is expected in the following summers
- Initial activities will focus on extending current 2D AFRL models for potentially important effects
- New initiatives in high-fidelity modeling will provide reference cases for error assessment and initial validation of the models

