



University of Michigan, Ann Arbor, 29.08.10



Effective Closure Schemes for ICM Dynamics

Alexander Schekochihin (*Oxford*)

Matt Kunz (*Princeton*)

Francois Rincon (*Toulouse*)

Steve Cowley (*U.K.A.E.A. & Imperial*)

Mark Rosin (*UCLA & Livermore*)

Schekochihin *et al.*, *ApJ* **629**, 139 (2005)

Schekochihin & Cowley, *Phys. Plasmas* **13**, 056501 (2006)

Schekochihin *et al.*, *PRL* **100**, 081301 (2008)

Schekochihin *et al.*, *MNRAS* **405**, 291 (2010)

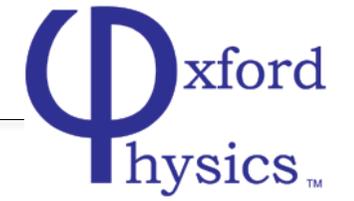
Rosin *et al.*, *MNRAS* **413**, 7 (2011)

Kunz *et al.*, *MNRAS* **410**, 2446 (2011)

Rincon *et al.*, in preparation (2012)



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$$\mu = \frac{mv_{\perp}^2}{2B}$$

[Kulsrud (1997)]





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Qxford
Physics™



$$\mu = \frac{mv_{\perp}^2}{2B}$$

[Kulsrud (1997)]



Equations

To describe the dynamics of the ICM, we write evolution equations for moments of the particle distribution and magnetic fields:

$$\frac{dn}{dt} = -n \nabla \cdot \mathbf{u} \qquad \frac{d}{dt} = \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$$

$$m_i n_i \frac{d\mathbf{u}}{dt} = -\nabla \cdot \left(\mathbf{P} + \left[\frac{B^2}{8\pi} - \frac{\mathbf{B}\mathbf{B}}{4\pi} \right] \right)$$

$$\frac{\partial \mathbf{B}}{\partial t} = -c \nabla \times \mathbf{E} = \nabla \times (\mathbf{u} \times \mathbf{B}) + [\text{FLR}]$$

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$$\frac{d\mathbf{B}}{dt} = \mathbf{B} \cdot \nabla \mathbf{u} - \mathbf{B} \nabla \cdot \mathbf{u} + [\text{FLR}]$$

Pressure Tensor

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$$\frac{d\mathbf{B}}{dt} = \mathbf{B} \cdot \nabla \mathbf{u} - \mathbf{B} \nabla \cdot \mathbf{u} + [\text{FLR}]$$

$$\begin{aligned} \mathbf{P} &= \sum_s \mathbf{P}_s = \sum_s m_s \int d^3 \mathbf{w} \mathbf{w} \mathbf{w} f_s(t, \mathbf{r}, \mathbf{w}) & \mathbf{w} &= \mathbf{v} - \mathbf{u} \\ &= p_{\perp} (\mathbf{l} - \mathbf{b}\mathbf{b}) + p_{\parallel} \mathbf{b}\mathbf{b} + [\text{FLR}] \end{aligned}$$

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$$\frac{d\mathbf{B}}{dt} = \mathbf{B} \cdot \nabla \mathbf{u} - \mathbf{B} \nabla \cdot \mathbf{u} + [\text{FLR}]$$

$$p_{\perp} \frac{d}{dt} \ln \frac{p_{\perp}}{nB} = -\nu(p_{\perp} - p_{\parallel}) + [\text{heat fluxes}] \qquad \text{conservation of}$$

$$p_{\parallel} \frac{d}{dt} \ln \frac{p_{\parallel} B^2}{n^2} = -2\nu(p_{\parallel} - p_{\perp}) + [\text{heat fluxes}] \qquad \mu = \frac{mv_{\perp}^2}{2B}$$

Typically $p_{\perp} - p_{\parallel} \ll p$ (tbc)

Also ignore $d \ln n / dt$ for simplicity (wrong, tech. speaking)

[AAS *et al.*, *MNRAS* **405**, 291 (2010)]

Heating and Pressure Anisotropy

To describe the dynamics of the ICM, we write evolution equations for moments of the particle distribution and magnetic fields:

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$$\frac{d\mathbf{B}}{dt} = \mathbf{B} \cdot \nabla \mathbf{u}$$

$$\frac{3}{2} n \frac{dT}{dt} = \underbrace{-\nabla \cdot \mathbf{q}}_{\text{heat flux}} + \underbrace{(p_{\perp} - p_{\parallel}) \frac{d \ln B}{dt}}_{\text{viscous heating}} - \underbrace{n_i n_e \Lambda}_{\text{cooling}} \quad p = nT$$

$$\frac{d(p_{\perp} - p_{\parallel})}{dt} = 3p \frac{d \ln B}{dt} - 3\nu(p_{\perp} - p_{\parallel}) + [\text{heat fluxes}]$$

Typically $p_{\perp} - p_{\parallel} \ll p$ (tbc)

Also ignore $d \ln n / dt$ for simplicity (wrong, tech. speaking)

[AAS *et al.*, *MNRAS* **405**, 291 (2010)]

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$$\Delta = \frac{p_{\perp} - p_{\parallel}}{p} \approx \frac{1}{\nu} \left(\frac{d \ln B}{dt} + \dots \right)$$

Pressure Anisotropy

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 \end{aligned}$$

$p = nT$

↑
 Braginskii
 viscosity

$$\Delta = \frac{p_{\perp} - p_{\parallel}}{p} \approx \frac{1}{\nu} \left(\frac{d \ln B}{dt} + \dots \right) = \frac{\mathbf{b}\mathbf{b} : \nabla \mathbf{u}}{\nu}$$

Instabilities

$$m_i n_i \frac{d\mathbf{u}}{dt} = -\nabla \left(p_{\perp} + \frac{B^2}{8\pi} \right) + \nabla \cdot \left[\mathbf{b}\mathbf{b} \left(p\Delta + \frac{B^2}{4\pi} \right) + [\text{FLR}] \right]$$

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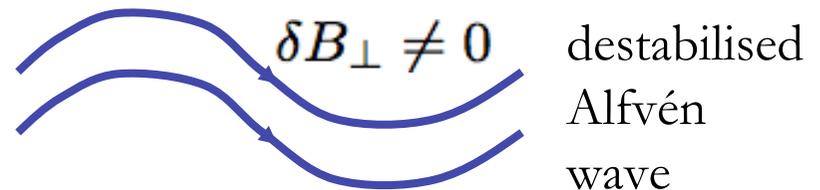
heat flux
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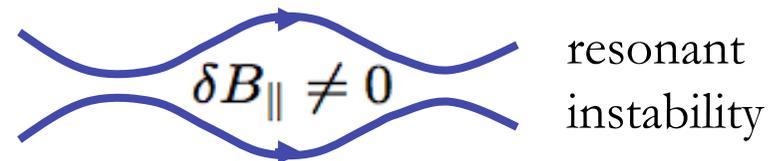
These equations are unstable to fast, short-scale perturbations:

$$\Delta < -\frac{2}{\beta} \quad \text{FIREHOSE}$$



$$\Delta \gtrsim \frac{1}{\beta} \quad \text{MIRROR}$$

(kinetic! but a wimpy fluid version exists)



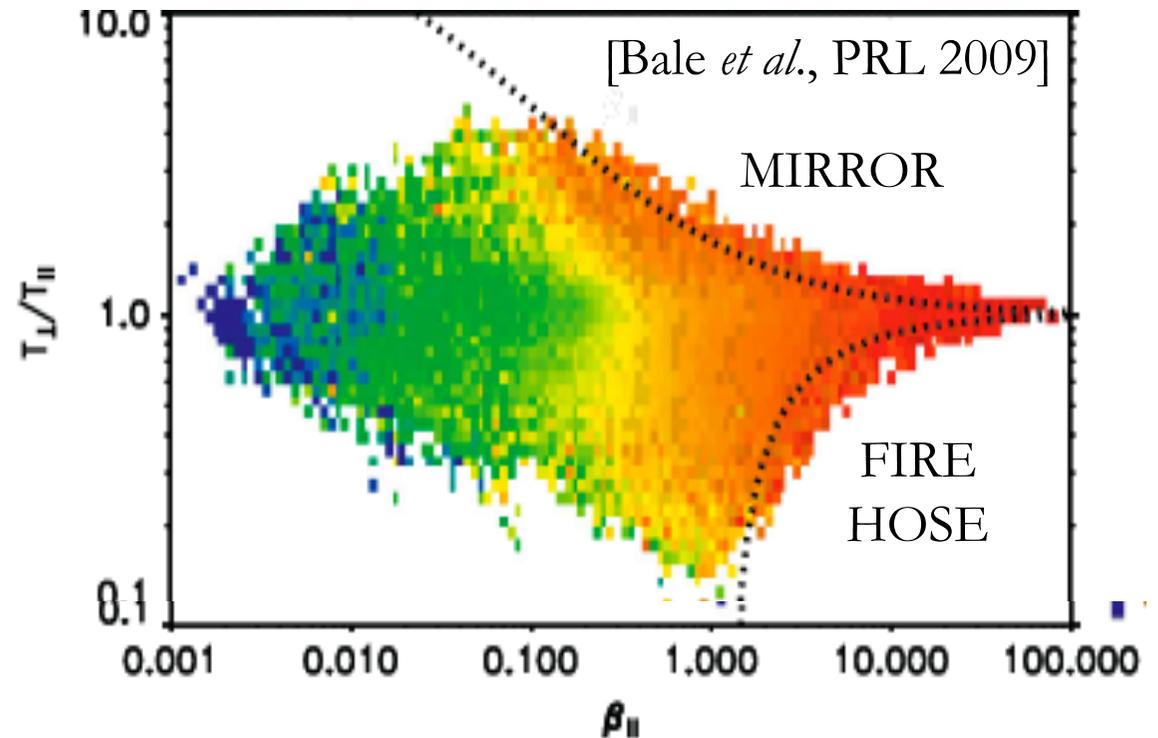
Marginality

For typical **cluster** parameters:

$$\Delta \sim \frac{1}{\beta} \sim 0.01$$

We know large scales (local equilibrium) will be marginal, but **how to model this depends on how marginality is achieved**

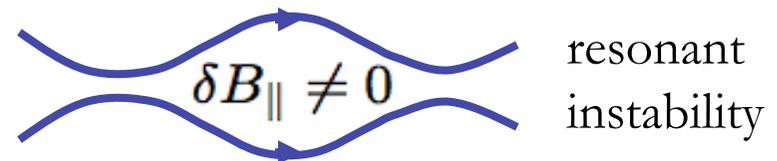
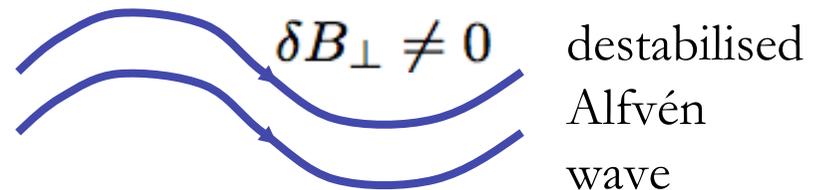
In the **solar wind**:



$$\Delta < -\frac{2}{\beta} \quad \text{FIREHOSE}$$

$$\Delta \gtrsim \frac{1}{\beta} \quad \text{MIRROR}$$

(kinetic! but a wimpy fluid version exists)

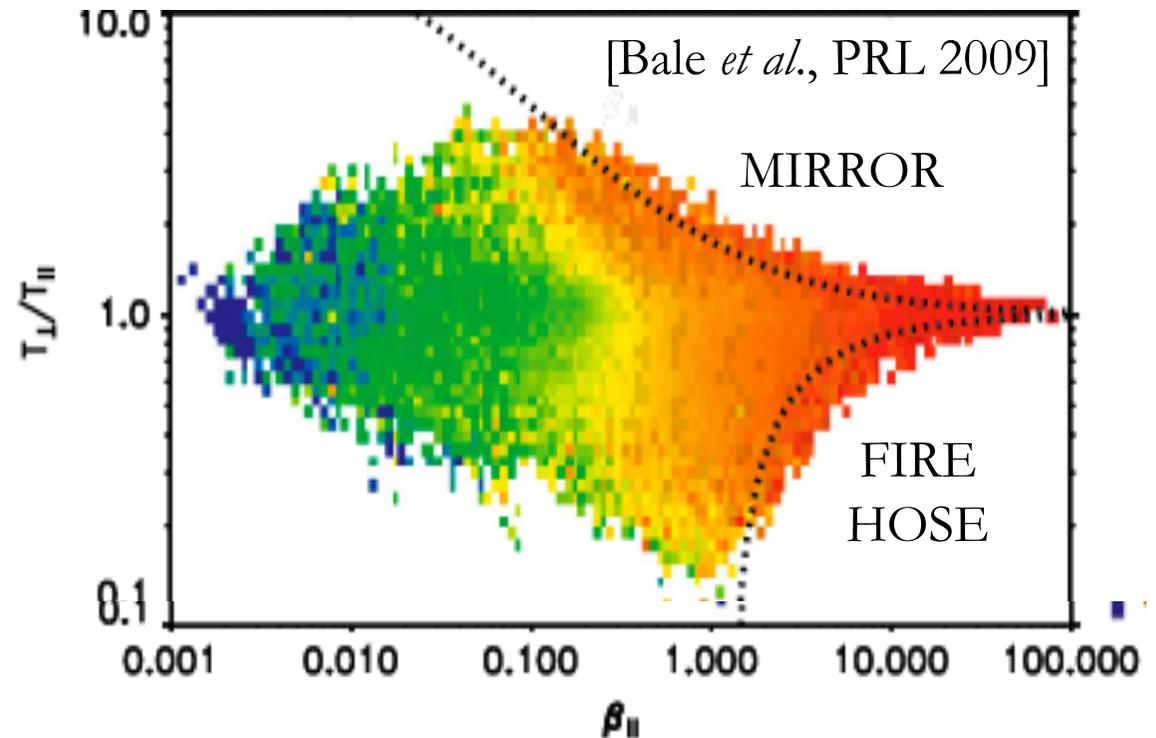


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In the **solar wind**:



NB: The reason you care about this is that you can't move anything in the ICM without stretching/ (de)compressing the m . field. This has to be consistent with the conservation of $\mu = mv_{\perp}^2/2B$ for each particle (so even weak B matters!) Pressure anisotropies and the resulting instabilities are the ICM's way of satisfying this constraint.

Closure

$$m_i n_i \frac{d\mathbf{u}}{dt} = -\nabla \left(p_{\perp} + \frac{B^2}{8\pi} \right) + \nabla \cdot \left[\mathbf{bb} \left(p\Delta + \frac{B^2}{4\pi} \right) + [\text{FLR}] \right]$$

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heat flux
viscous heating

Braginskii
viscosity

Closure must enforce:

$$\Delta = \frac{p_{\perp} - p_{\parallel}}{p} \approx \frac{1}{\nu} \left(\frac{d \ln B}{dt} + \dots \right) = \frac{\mathbf{bb} : \nabla \mathbf{u}}{\nu} \in \left[-\frac{2}{\beta}, \frac{1}{\beta} \right]$$

➤ Enhanced particle scattering isotropises pressure

Closure provides more collisions:
 $\nu \rightarrow \nu_{\text{eff}} \gg \nu$ [Sharma et al. 2006; AAS & Cowley 2006]

➤ Magnetic field structure and evolution modified to offset change

Closure limits rate of strain:
 $\frac{d \ln B}{dt} = \mathbf{bb} : \nabla \mathbf{u} \in \frac{\nu}{\beta} [-2, 1]$
 [Kunz et al. 2011]

$$m_i n_i \frac{d\mathbf{u}}{dt} = -\nabla \left(p_{\perp} + \frac{B^2}{8\pi} \right) + \nabla \cdot \left[\mathbf{bb} \left(p\Delta + \frac{B^2}{4\pi} \right) + [\text{FLR}] \right]$$

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Implementation: $\nu_{\text{eff}} = \nu_{\text{Coulomb}}$ if $\Delta \in [-2, 1]/\beta$
 (in CGL eqns) $\nu_{\text{eff}} = \mathcal{V} \gg \nu_{\text{Coulomb}}$ if $\Delta \notin [-2, 1]/\beta$

So Δ does not limit rate of change of magnetic field;
 (parallel) viscosity p/ν_{eff} **drops** to naught
 (\Rightarrow smaller scales, larger rates of strain develop, $\text{Re}_{\text{eff}} \rightarrow \infty$)

$$m_i n_i \frac{d\mathbf{u}}{dt} = -\nabla \left(p_{\perp} + \frac{B^2}{8\pi} \right) + \nabla \cdot \left[\mathbf{bb} \left(p\Delta + \frac{B^2}{4\pi} \right) + [\text{FLR}] \right]$$

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Implementation: if $\mathbf{bb} : \nabla \mathbf{u} \notin [-2, 1](\nu/\beta)$ add large effective viscosity in momentum eqn to damp excess rate of strain

(cf. LES models/Syrovatskii)

So rate of change of magnetic field stays $\frac{d \ln B}{dt} = \nu \Delta \in \frac{\nu}{\beta} [-2, 1]$

viscosity of supercritical motions **increases**

(motions stay large-scale, $\text{Re}_{\text{eff}} \rightarrow 0$)

Implications for Heating

Kunz et al. closure

$$Q^+ = p\Delta \frac{d \ln B}{dt} = p\nu\Delta^2 \sim p \frac{\nu}{\beta^2}$$

$$\sim 10^{-25} \left(\frac{B}{10 \mu\text{G}} \right)^4 \left(\frac{T}{2 \text{keV}} \right)^{-5/2} \frac{\text{erg}}{\text{s cm}^3}$$

viscous heating

$$Q^- \sim 10^{-25} \left(\frac{n_e}{0.1 \text{cm}^{-3}} \right)^2 \left(\frac{T}{2 \text{keV}} \right)^{1/2} \frac{\text{erg}}{\text{s cm}^3}$$

Bremsstrahlung
cooling

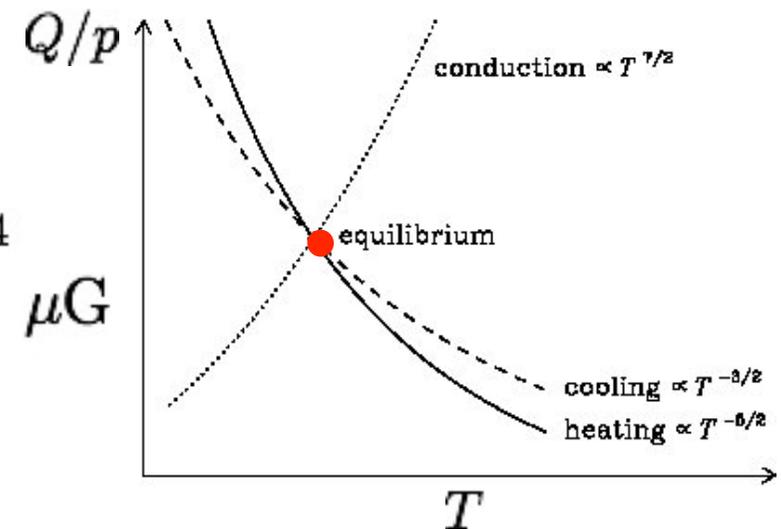
➤ Thermally stable ICM

➤ If $Q^+ \sim Q^-$,

$$B \sim 10 \left(\frac{n_e}{0.1 \text{cm}^{-3}} \right)^{1/2} \left(\frac{T}{2 \text{keV}} \right)^{3/4} \mu\text{G}$$

➤ If $m_i n_i u^2 / 2 \sim B^2 / 8\pi$,

$$u \sim 10^2 \left(\frac{T}{2 \text{keV}} \right)^{3/4} \frac{\text{km}}{\text{s}}$$



Implications for Heating

Sharma et al. closure

$$Q^+ = p\Delta \frac{d \ln B}{dt} = p\nu_{\text{eff}}\Delta^2 \sim p \frac{\Omega_i}{\beta^4} \quad \nu_{\text{eff}} \sim \gamma_{\text{mirror}} \sim \Omega_i \Delta^2$$

$$\sim 10^{58} \left(\frac{B}{10 \mu\text{G}} \right)^9 \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{-4} \left(\frac{T}{2 \text{ keV}} \right)^{-4} \frac{\text{erg}}{\text{s cm}^3}$$

$$Q^- \sim 10^{-25} \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^2 \left(\frac{T}{2 \text{ keV}} \right)^{1/2} \frac{\text{erg}}{\text{s cm}^3} \quad \text{Bremsstrahlung cooling}$$

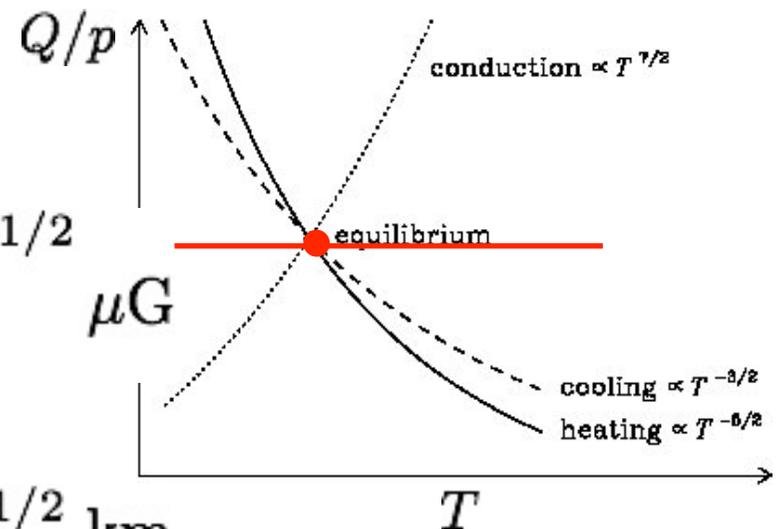
➤ **Thermally unstable**

➤ If $Q^+ \sim Q^-$,

$$B \sim 10^{-8} \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{2/3} \left(\frac{T}{2 \text{ keV}} \right)^{1/2} \mu\text{G}$$

➤ If $m_i n_i u^2 / 2 \sim B^2 / 8\pi$,

$$u \sim 10^{-2} \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{1/6} \left(\frac{T}{2 \text{ keV}} \right)^{1/2} \frac{\text{km}}{\text{s}}$$



Implications for Heating

Sharma et al. closure

$$Q^+ = p\Delta \frac{d \ln B}{dt} = p\nu_{\text{eff}} \Delta^2 \sim p \frac{\Omega_i}{\beta^4}$$

$$\nu_{\text{eff}} \sim \gamma_{\text{mirror}} \sim \Omega_i \Delta^2$$

Of course, this is a naive estimate!

In fact,

$$\gamma_{\text{mirror}} \sim \Omega_i \left(\Delta - \frac{1}{\beta} \right)^2$$

so can bring ν_{eff} down by staying very close to threshold,

$$\Delta - \frac{1}{\beta} \ll \frac{1}{\beta}$$

Can't make progress without microphysical theory of ν_{eff} ...

NB: Since this closure implies a dramatic reduction of viscosity near thresholds, this becomes very difficult to resolve numerically, so typically one just uses a large ν_{eff} , but not one that depends on Δ , β and Ω_i , which changes the dynamics (also heating, dynamo)

Implications for Heating

$$Q^+ = p\Delta \frac{d \ln B}{dt} = p\nu\Delta^2 \sim p \frac{\nu}{\beta^2}$$

One might say: *surely, heating = energy injection,*

so how can it be limited by microphysics?

- System can have “impedance”: how much energy it will accept depends on local value of β
- If you take the view that there is no impedance, then

$$Q^{\text{in}} \sim \frac{m_i n_i u^3}{L} \sim \frac{m_i n_i}{L} \left(\frac{B}{4\pi m_i n_i} \right)^3 \sim Q^+(B, T) \sim Q^-(n_e, T)$$

Using Kunz et al. scalings, $T \sim 2 \left(\frac{L}{0.2 \text{ kpc}} \frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{4/7} \text{ keV}$

(this is not terribly useful as we do not know the injection scale;
alternatively, can use this to predict L from observations)

[Kunz *et al.*, *MNRAS* **410**, 2446 (2011)]

Implications for Turbulent Dynamo

$$\frac{d \ln B}{dt} = \mathbf{bb} : \nabla \mathbf{u} = \nu \Delta \in \frac{\nu}{\beta} [-2, 1]$$

Suppose there is enough stirring to keep Δ at the threshold

$$\frac{d \ln B}{dt} \sim \frac{\nu}{\beta} = \frac{\nu}{8\pi p} B^2$$

Explosive growth, but (using **Kunz et al. closure**) it takes a long time to get going:

$$t_{\text{growth}} \sim \frac{\beta_0}{\nu} \sim \beta_0 \times 10 \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{-1} \left(\frac{T}{2 \text{ keV}} \right)^{3/2} \text{ yrs}$$

$$t_{\text{cool}} \sim 10^8 \left(\frac{n_e}{0.1 \text{ cm}^{-3}} \right)^{-1} \left(\frac{T}{2 \text{ keV}} \right)^{1/2} \text{ yrs}$$

So this can efficiently restore fields from $B \gtrsim 10^{-8} \text{ G}$
to current values $B \sim 10^{-5} \text{ G}$,

but for growth from a tiny seed, need a different mechanism

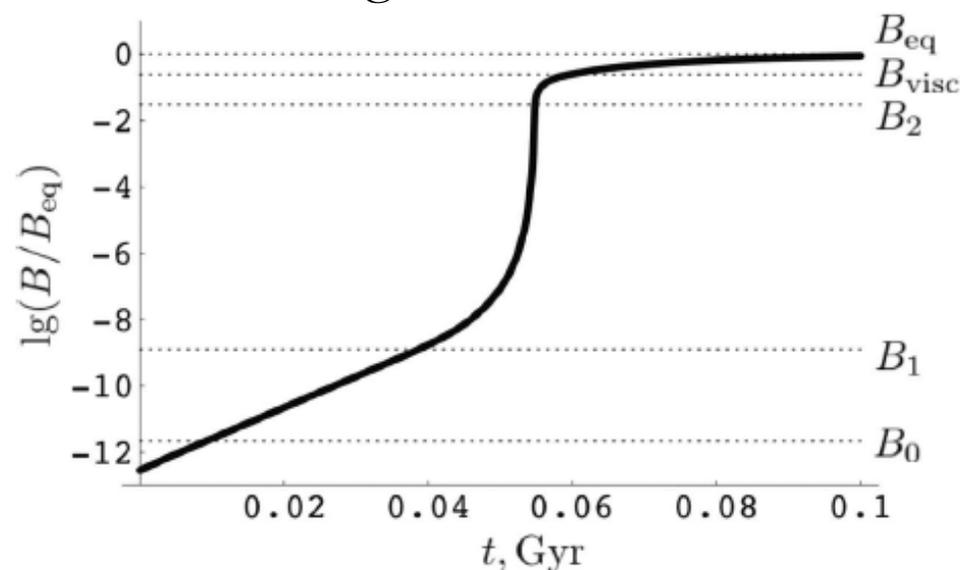
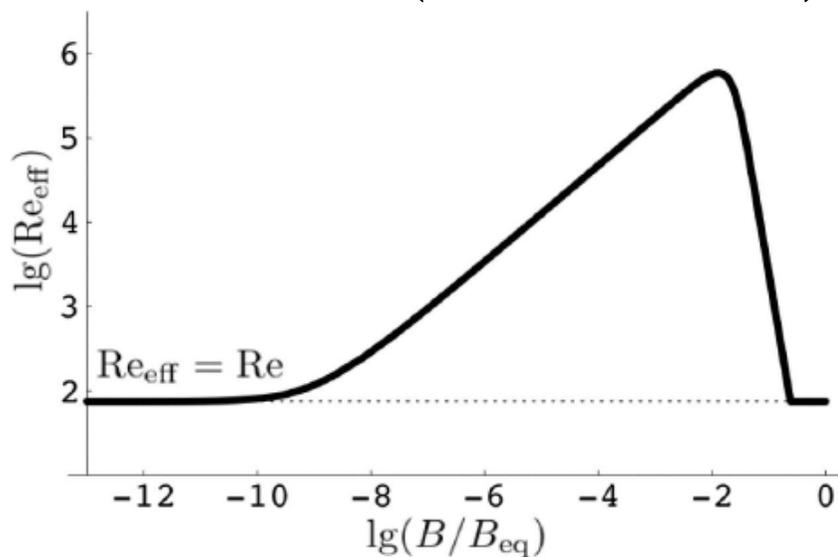
Implications for Turbulent Dynamo

$$\frac{d \ln B}{dt} = \mathbf{bb} : \nabla \mathbf{u} = \nu \Delta \in \frac{\nu}{\beta} [-2, 1]$$

Sharma et al. closure: $\nu \rightarrow \nu_{\text{eff}} = \nu + \Omega_i \left(\Delta - \frac{1}{\beta} \right)^2$ (AAS & Cowley 2006 version)

$$\frac{d \ln B}{dt} \sim \frac{u}{L} \text{Re}_{\text{eff}}^{1/2} \sim \frac{u}{L} \left(\frac{uL}{v_{\text{thi}}^2} \nu_{\text{eff}} \right)^{1/2}$$

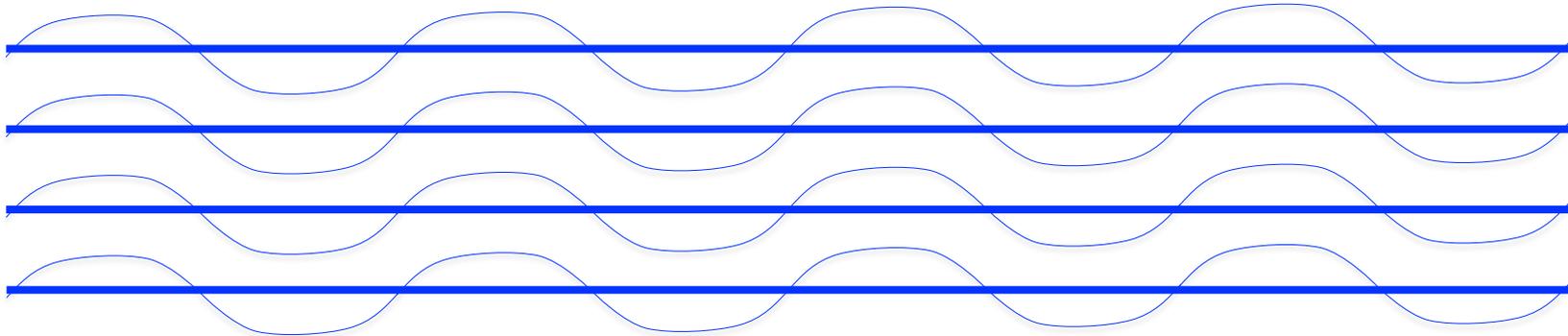
Explosive growth again and can massage the model to grow from small seeds ($B \sim 10^{-17} \text{ G}$) to observed strengths in short times:



Microphysics: Firehose

$$\overline{B^2} = \overline{|\mathbf{B}_0 + \delta\mathbf{B}_\perp|^2} = B_0^2 + \overline{|\delta\mathbf{B}_\perp|^2}$$

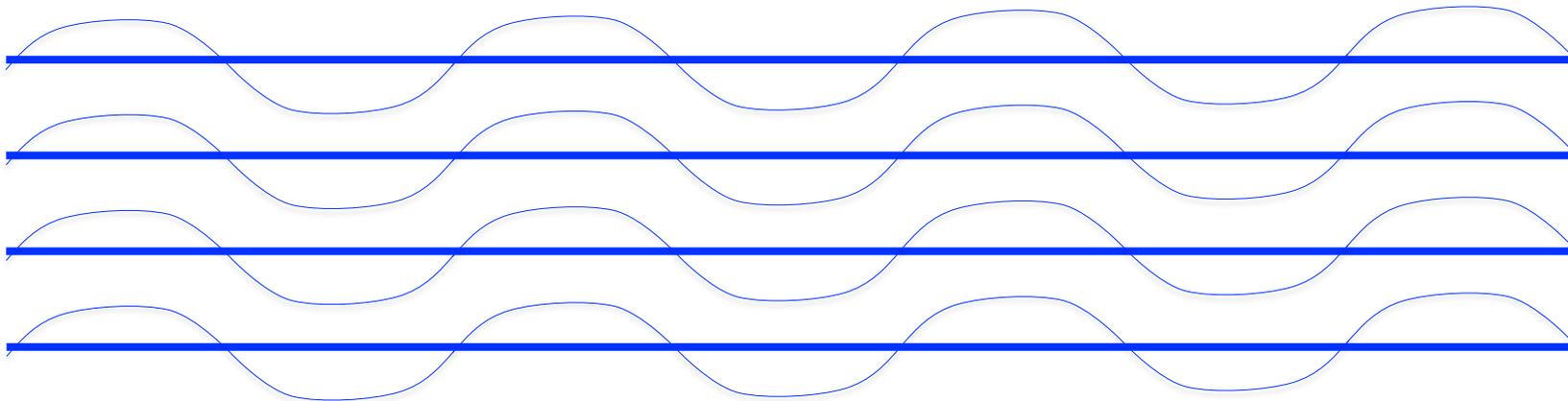
$$\Delta = \frac{1}{\nu} \frac{d \ln \overline{B}}{dt} = \frac{1}{\nu} \left(- \underbrace{\left| \frac{d \ln B_0}{dt} \right|}_{\text{macroscale field (large but slow)}} + \underbrace{\frac{1}{2} \frac{d}{dt} \frac{\overline{|\delta\mathbf{B}_\perp|^2}}{B_0^2}}_{\text{microscale fluctuations (small but fast)}} \right) \rightarrow -\frac{2}{\beta}$$



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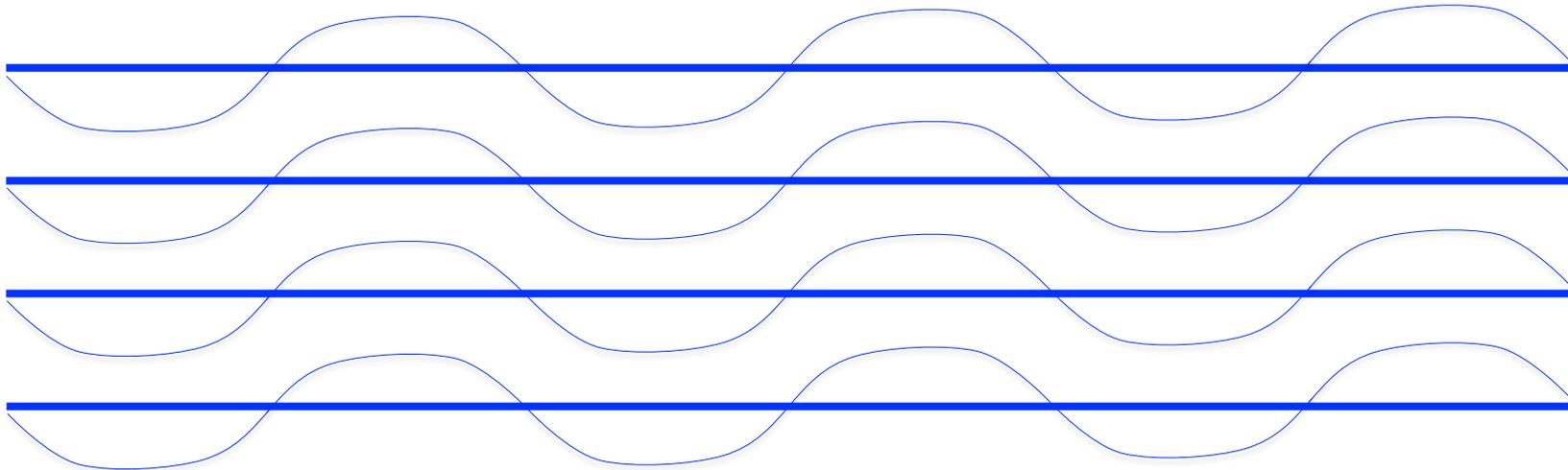
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macroscale field
(large but slow)

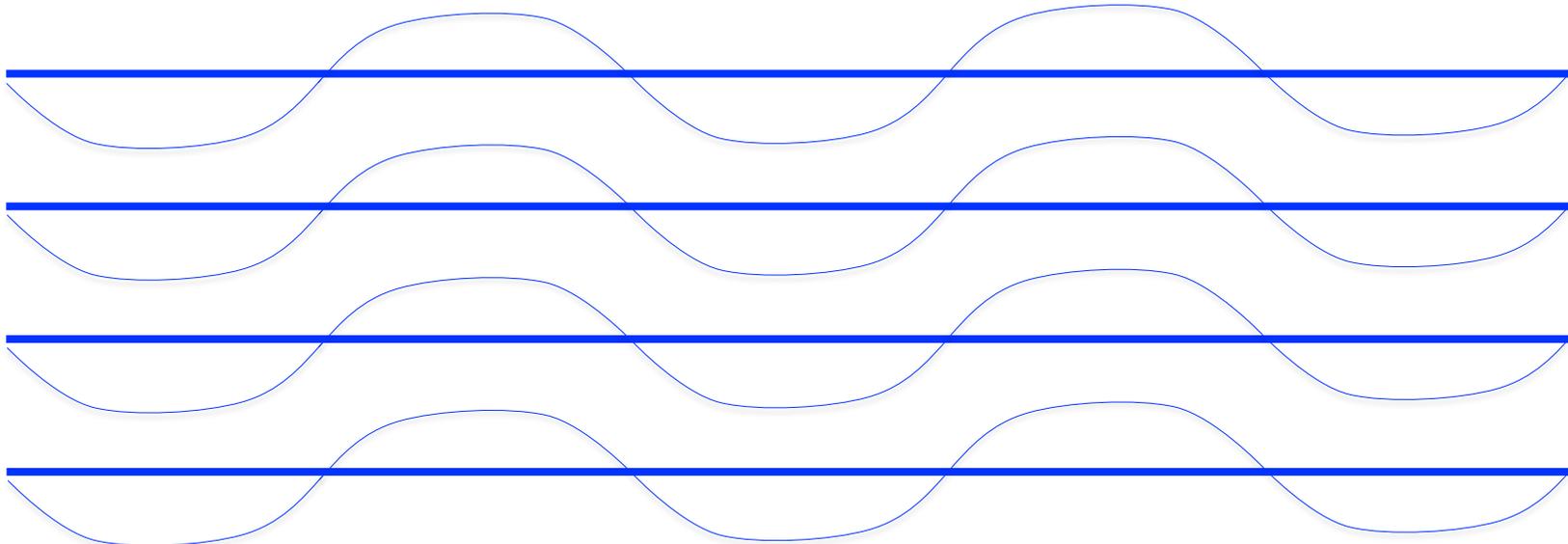
microscale fluctuations
(small but fast)



Microphysics: Firehose

$$\overline{B^2} = \overline{|\mathbf{B}_0 + \delta\mathbf{B}_\perp|^2} = B_0^2 + \overline{|\delta\mathbf{B}_\perp|^2}$$

$$\Delta = \frac{1}{\nu} \frac{d \ln \overline{B}}{dt} = \frac{1}{\nu} \left(\underbrace{- \left| \frac{d \ln B_0}{dt} \right|}_{\substack{\text{macroscale} \\ \text{field} \\ \text{(large but slow)}}} + \underbrace{\frac{1}{2} \frac{d}{dt} \frac{\overline{|\delta\mathbf{B}_\perp|^2}}{B_0^2}}_{\substack{\text{microscale} \\ \text{fluctuations} \\ \text{(small but fast)}}} \right) \rightarrow -\frac{2}{\beta}$$



Microphysics: Firehose

$$\overline{B^2} = \overline{|\mathbf{B}_0 + \delta\mathbf{B}_\perp|^2} = B_0^2 + \overline{|\delta\mathbf{B}_\perp|^2}$$

$$\Delta = \frac{1}{\nu} \frac{d \ln \overline{B}}{dt} = \frac{1}{\nu} \left(- \left| \frac{d \ln B_0}{dt} \right| + \frac{1}{2} \frac{d}{dt} \frac{\overline{|\delta\mathbf{B}_\perp|^2}}{B_0^2} \right) \rightarrow -\frac{2}{\beta}$$

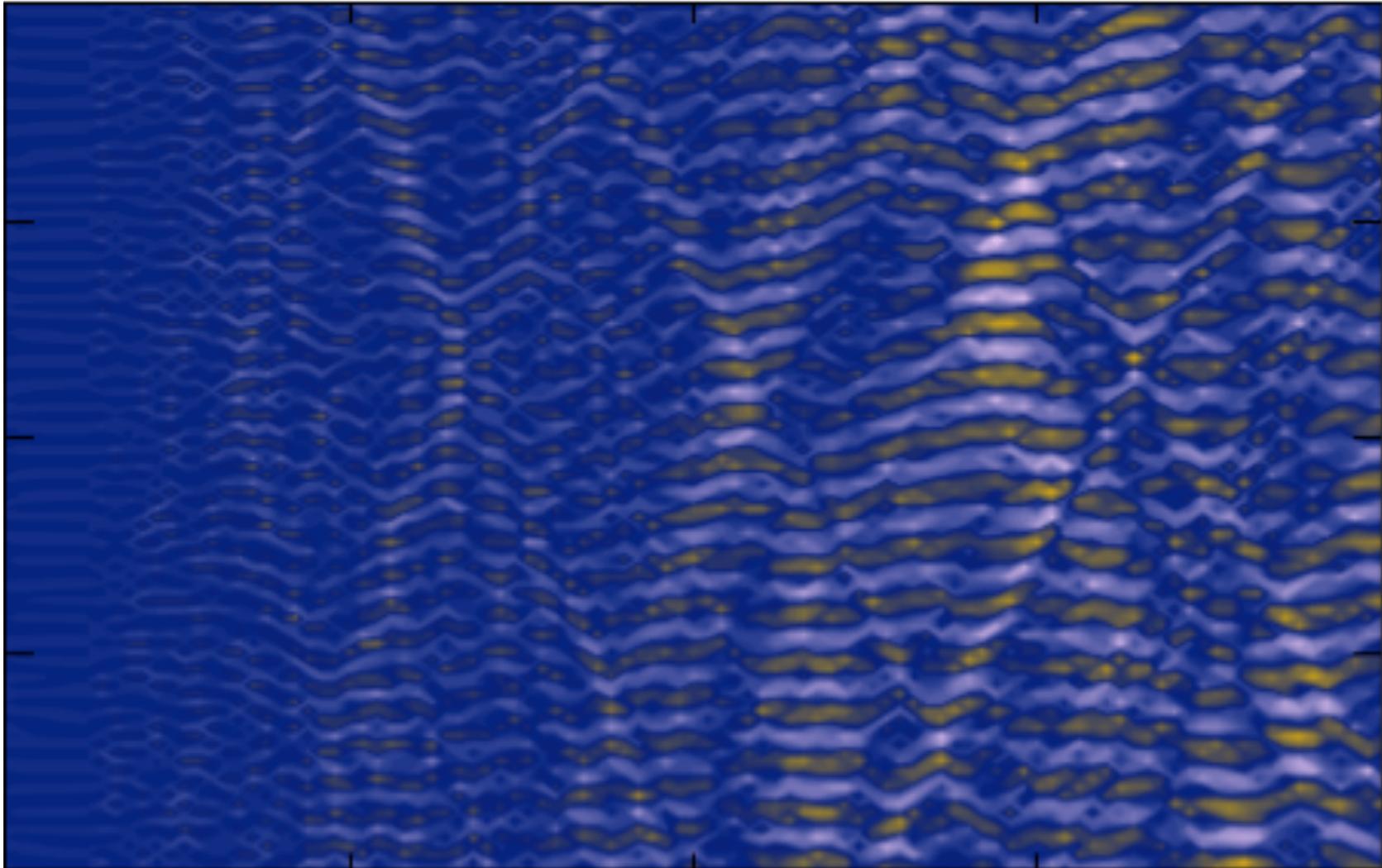
➤ Amplitude $\frac{\overline{|\delta\mathbf{B}_\perp|^2}}{B_0^2} = \left(\left| \frac{d \ln B_0}{dt} \right| - \frac{2\nu}{\beta} \right) t$

➤ Scale $k_{\parallel} \rho_i = 2\sqrt{2} \left| \Delta + \frac{2}{\beta} \right|^{1/2} \sim \frac{1}{\sqrt{\Omega_i t}} \ll 1$

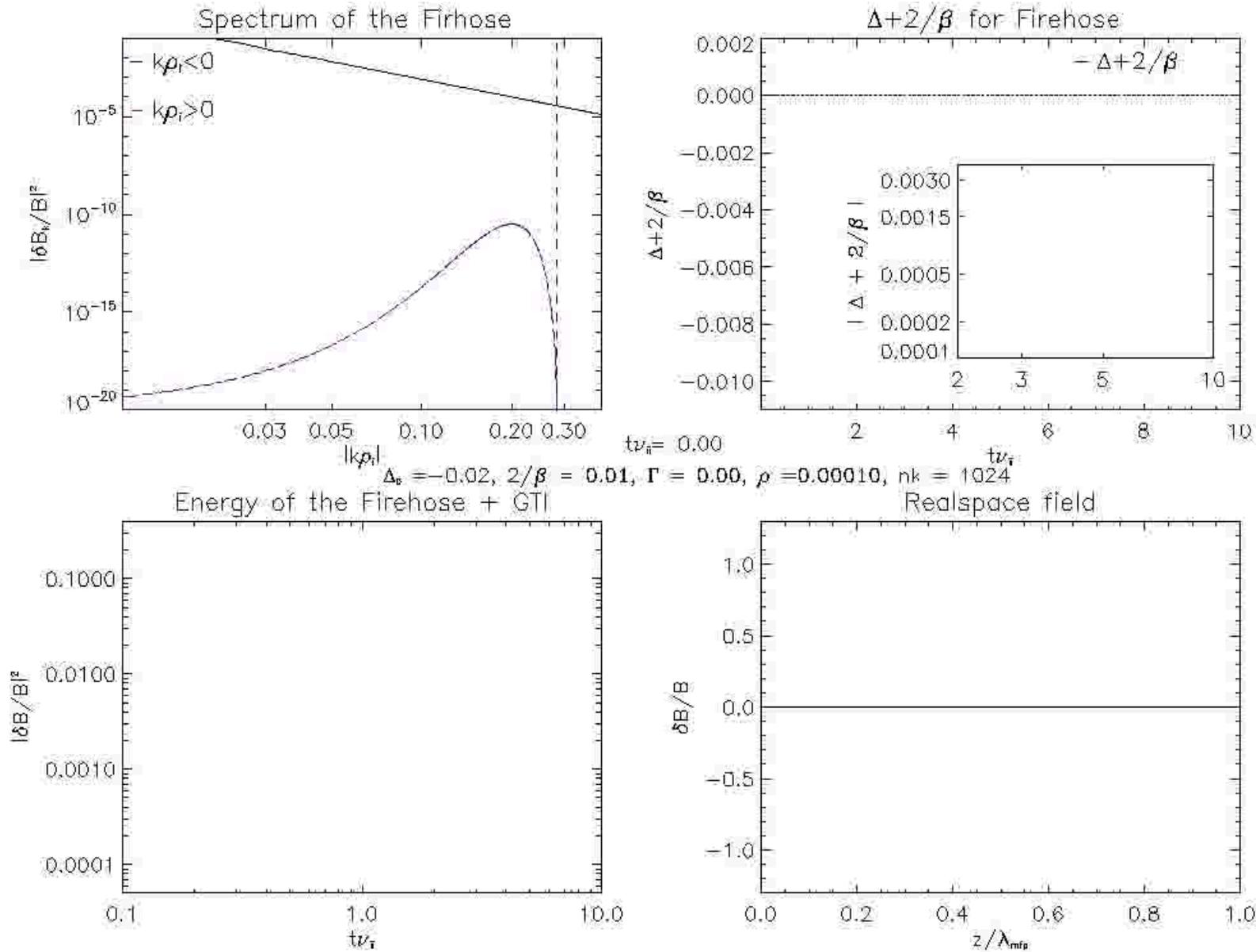
(scale too large to break conservation of μ , so **no scattering**)

Microphysics: Firehose

$$\overline{B^2} = \overline{|\mathbf{B}_0 + \delta\mathbf{B}_\perp|^2} = B_0^2 + \overline{|\delta\mathbf{B}_\perp|^2}$$



Microphysics: Firehose



Microphysics: Mirror

$$\bar{B} = B_0 + \overline{\delta B_{\parallel}}$$

$$\Delta = \frac{1}{\nu} \frac{d \ln \bar{B}}{dt} = \frac{1}{\nu} \left(\frac{d \ln B_0}{dt} + \frac{d \overline{\delta B_{\parallel}}}{dt B_0} \right) \rightarrow \frac{1}{\beta}$$

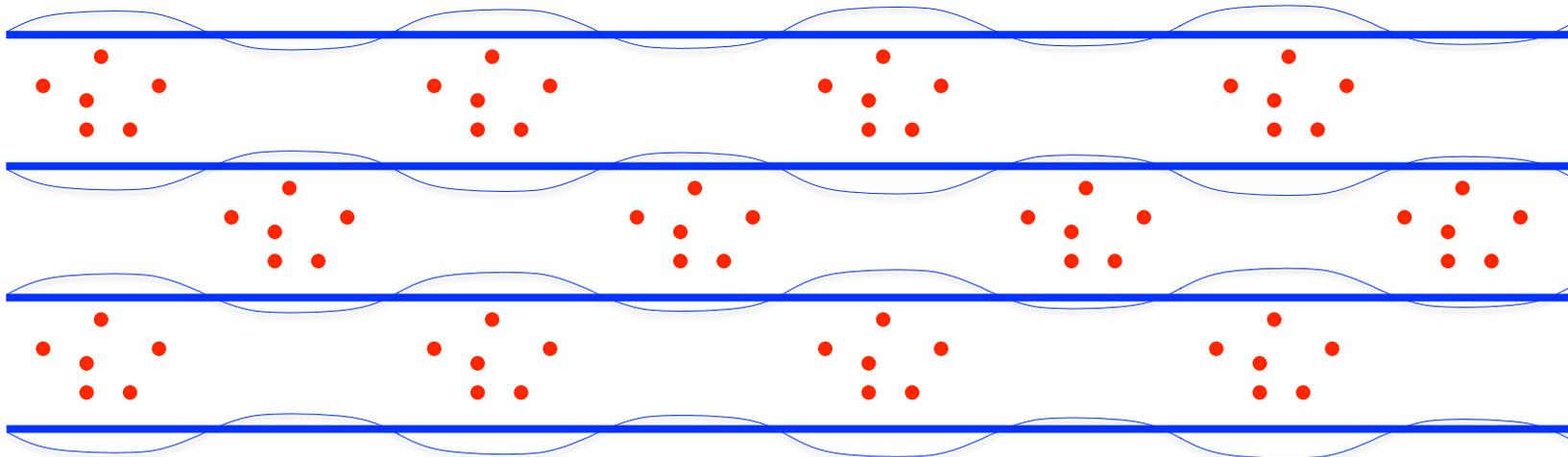
mirror-trapped
particles in holes
(fraction $\sim |\delta B_{\parallel}/B_0|^{1/2}$)

Microphysics: Mirror

$$\bar{B} = B_0 + \overline{\delta B_{\parallel}}$$

$$\Delta = \frac{1}{\nu} \frac{d \ln \bar{B}}{dt} \sim \frac{1}{\nu} \left(\frac{d \ln B_0}{dt} - \frac{d}{dt} \left| \frac{\delta B_{\parallel}}{B_0} \right|^{3/2} \right) \rightarrow \frac{1}{\beta}$$

mirror-trapped
particles in holes
(fraction $\sim |\delta B_{\parallel}/B_0|^{1/2}$)

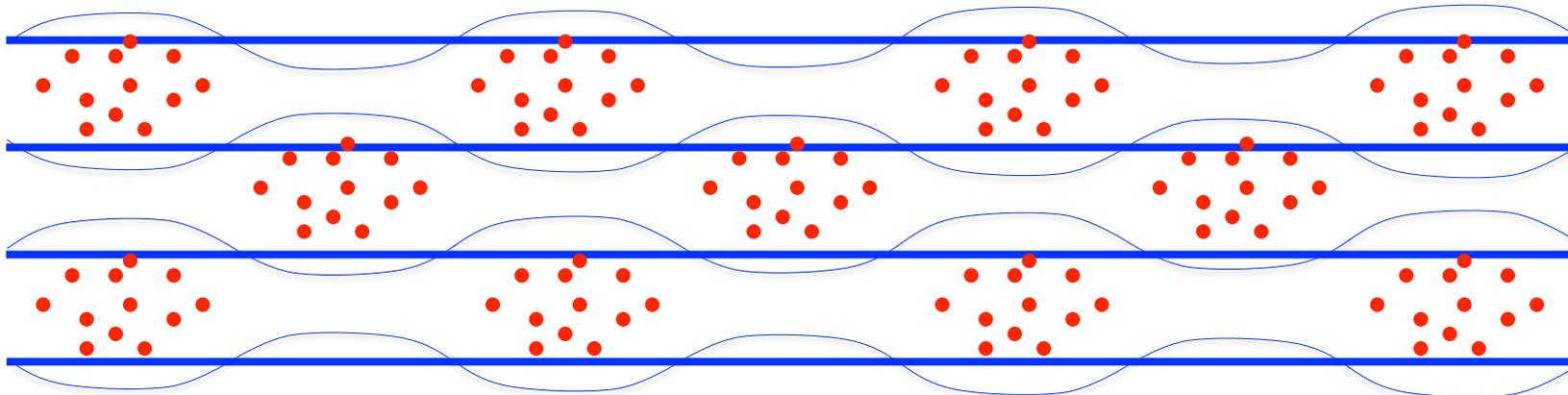


Microphysics: Mirror

$$\bar{B} = B_0 + \overline{\delta B_{\parallel}}$$

$$\Delta = \frac{1}{\nu} \overline{\frac{d \ln B}{dt}} \sim \frac{1}{\nu} \left(\frac{d \ln B_0}{dt} - \frac{d}{dt} \left| \frac{\delta B_{\parallel}}{B_0} \right|^{3/2} \right) \rightarrow \frac{1}{\beta}$$

mirror-trapped
particles in holes
(fraction $\sim |\delta B_{\parallel}/B_0|^{1/2}$)

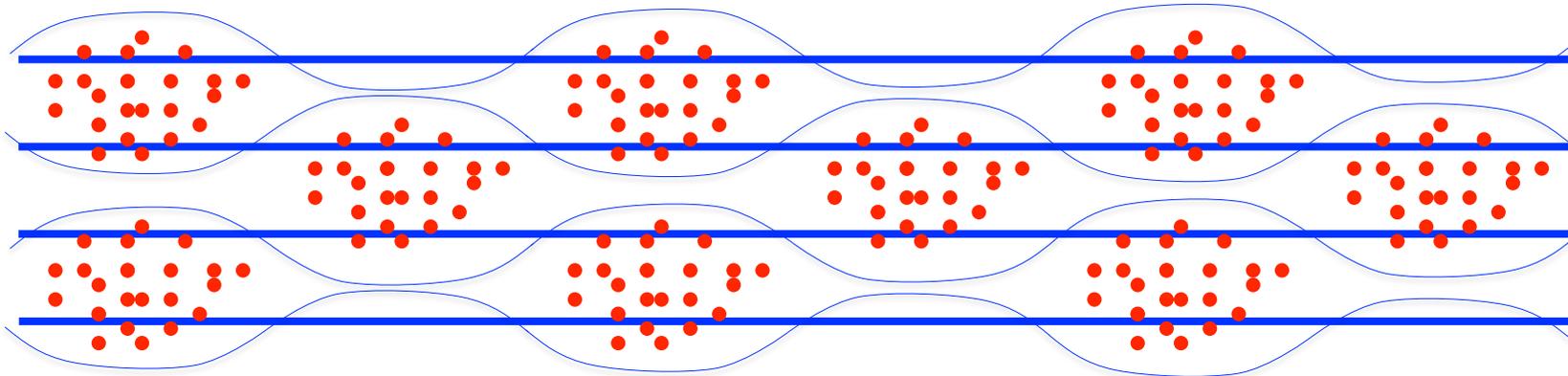


Microphysics: Mirror

$$\bar{B} = B_0 + \overline{\delta B_{\parallel}}$$

$$\Delta = \frac{1}{\nu} \overline{\frac{d \ln B}{dt}} \sim \frac{1}{\nu} \left(\frac{d \ln B_0}{dt} - \frac{d}{dt} \left| \frac{\delta B_{\parallel}}{B_0} \right|^{3/2} \right) \rightarrow \frac{1}{\beta}$$

mirror-trapped
particles in holes
(fraction $\sim |\delta B_{\parallel}/B_0|^{1/2}$)



$$\bar{B} = B_0 + \overline{\delta B_{\parallel}}$$

$$\Delta = \frac{1}{\nu} \frac{d \ln \bar{B}}{dt} \sim \frac{1}{\nu} \left(\frac{d \ln B_0}{dt} - \frac{d}{dt} \left| \frac{\delta B_{\parallel}}{B_0} \right|^{3/2} \right) \rightarrow \frac{1}{\beta}$$

mirror-trapped
particles in holes
(fraction $\sim |\delta B_{\parallel}/B_0|^{1/2}$)

➤ Amplitude $\left| \frac{\delta B_{\parallel}}{B_0} \right| \sim \left[\left(\frac{d \ln B_0}{dt} - \frac{\nu}{\beta} \right) t \right]^{2/3}$

➤ Scale $k_{\parallel} \rho_i \sim \Delta - \frac{1}{\beta} \ll 1$

(scale too large to break conservation of μ , so **no scattering**)

Conclusions

I have no conclusions yet...



Conclusions

I have no conclusions yet... OK, here are some:

- Moving magnetised ICM around at large scales requires a closure model for the net effect of pressure-anisotropy-driven microscale instabilities
- The effective closure must keep pressure anisotropy within thresholds set by the local β [AAS *et al.*, *MNRAS* **405**, 291 (2010)]
- This can be achieved EITHER via locally enhanced collisionality [I] OR via controlling local rate of strain [II] (enhanced viscosity, LES-style)
- It matters which you choose:
 - Smaller [I] vs. larger [II] **viscosity**
 - Different predictions for **heating** [Kunz *et al.*, *MNRAS* **410**, 2446 (2011)] (only [II] gives thermally stable ICM as far as I can tell)
 - Turbulent **dynamo** is explosive in both cases, [AAS & Cowley, *Phys. Plasmas* **13**, 056501 (2006)] but with different time scales
- To the best my understanding of the microphysics, there is no anomalous scattering, so **I prefer closure [II]** [AAS *et al.*, *PRL* **100**, 081301 (2008); Rosin *et al.*, *MNRAS* **413**, 7 (2011)]